

# Trash Trekker

## **Project Description:**

This project developed a rover to sort garbage based on if it is metal or non-metal. The rover is equipped with ultrasonic sensors, a metal detector, a camera module, a temperature and humidity sensor, servo motors, DC motors, and an ESP32 microcontroller module for control and communication.

## **Student Team:**

**Anmol Singh**  
**Yatin Kumar**

## **Supervisor:**

**Mrs. Karen Craigs**

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