

# Scara Robot 4DOF

## Project Description:

This project is a SCARA robot with four degrees of freedom (4DOF) that aims to enable seamless pick-and-place operations within its designated workspace. An IIoT dashboard allows the user to control and monitor the process.

## Student Team:

**Harsh Sheth**

**Om Patel**

## Supervisor:

**Mr. Fabio Costa**

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